

GPS Heading/Yaw (aka Moving Baseline)

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PX4 Guide for RTK

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PX4 Firmware

GPS Heading with Dual u-blox F9P is supported in the both DroneCAN and UART version. The DroneCAN version requires a different firmware and can be found in the guide below.

https://docs.px4.io/main/en/gps_compass/u-blox_f9p_heading.html

https://docs.px4.io/main/en/advanced_features/rtk-gps.html

https://docs.px4.io/main/en/dronecan/holybro_h_rtk_zed_f9p_gps.html

Ardupilot Wiki for RTK

<https://ardupilot.org/copter/docs/common-gps-for-yaw.html>

<https://ardupilot.org/copter/docs/common-positioning-landing-page.html#rtk-gps>
